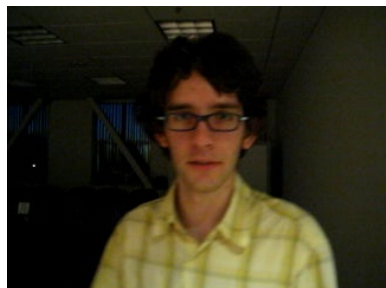
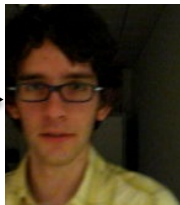


Current frame

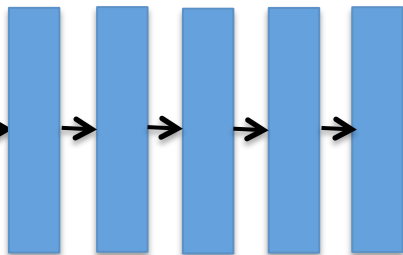


Crop

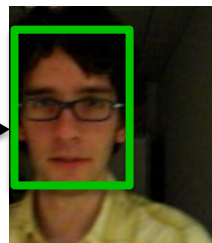
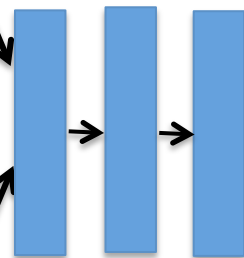
Search Region



Conv Layers



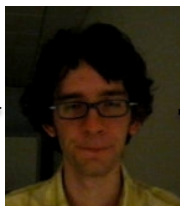
Fully-Connected Layers



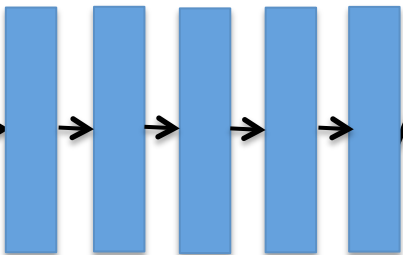
Predicted location of target within search region

Crop

What to track



Conv Layers



Previous frame

